# Contact Process in a Wedge 

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#### Abstract

We prove that the supercritical one-dimensional contact process survives in certain wedge-like space-time regions, and that when it survives it couples with the unrestricted contact process started from its upper invariant measure. As an application we show that a type of weak coexistence is possible in the nearest-neighbor "grass-bushes-trees" successional model introduced in Durrett and Swindle (Stoch. Proc. Appl. 37:19-31, 1991).


Keywords Contact process • Grass-bushes-trees

## 1 Introduction

The contact process of Harris (introduced in [6]) is a well known model of infection spread by contact. The one-dimensional model is a continuous time Markov process $\xi_{t}$ on $\{0,1\}^{\mathbb{Z}}$. For $x \in \mathbb{Z}, \xi_{t}(x)=1$ means the individual at site $x$ is infected at time $t$ while $\xi_{t}(x)=0$ means the individual is healthy. Infected individuals recover from their infection after an exponential time with mean 1 , independently of everything else. Healthy individuals become infected at a rate proportional to the number of infected neighbors. Alternatively, individuals (1's) die at rate one and give birth onto neighboring empty sites ( 0 's) at rate $\lambda$. If we let

[^0]$n_{i}(x, \xi)=\sum_{y:|y-x|=1} 1\{\xi(y)=i\}$, and $\lambda \geq 0$ the infection parameter, then the transitions at $x$ in state $\xi$ are
\[

$$
\begin{equation*}
1 \rightarrow 0 \text { at rate } 1 \quad \text { and } \quad 0 \rightarrow 1 \text { at rate } \lambda n_{1}(x, \xi) . \tag{1}
\end{equation*}
$$

\]

When convenient we will identify $\xi \in\{0,1\}^{\mathbb{Z}}$ with $\{x: \xi(x)=1\}$, and use the notation $\|\xi\|_{i}=\sum_{x} 1\{\xi(x)=i\}$.

Let $\xi_{t}^{0}$ denote the contact process with initial state $\xi_{0}^{0}=\{0\}$. The critical value $\lambda_{c}$ is defined by

$$
\begin{equation*}
\lambda_{c}=\inf \left\{\lambda \geq 0: P\left(\xi_{t}^{0} \neq \emptyset \text { for all } t \geq 0\right)>0\right\} . \tag{2}
\end{equation*}
$$

It is well known that $0<\lambda_{c}<\infty$, and that in the supercritical case $\lambda>\lambda_{c}$ there is a unique stationary distribution $v$ for $\xi_{t}$, called the upper invariant measure, with the property

$$
v\left(\xi:\|\xi\|_{1}=\infty\right)=1
$$

There are also well-defined "edge speeds." Let $\xi_{0}^{-}\left(\xi_{0}^{+}\right)$be the initial state given by $\xi_{0}^{-}=\mathbb{Z}^{-}$ $\left(\xi_{0}^{+}=\mathbb{Z}^{+}\right)$, and define the edge processes

$$
\begin{equation*}
r_{t}=\max \left\{x: \xi_{t}^{-}(x)=1\right\} \quad \text { and } \quad l_{t}=\min \left\{x: \xi_{t}^{+}(x)=1\right\} \tag{3}
\end{equation*}
$$

There is a strictly increasing function $\alpha:\left(\lambda_{c}, \infty\right) \rightarrow(0, \infty)$ such that for $\lambda>\lambda_{c}$

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{r_{t}}{t}=\alpha(\lambda) \quad \text { and } \quad \lim _{t \rightarrow \infty} \frac{l_{t}}{t}=-\alpha(\lambda) \text { a.s. } \tag{4}
\end{equation*}
$$

All of the above facts are contained in Chap. VI of [7] and Part I of [8]. See also Part I of [8] and the Bibliography there for many references to original papers.

The focus of this paper is a version of the contact process in which infection is restricted to certain space-time regions. In particular, we are interested in whether or not survival of the infection is possible in narrow, wedge-like regions, and, given survival, how does such a process behave. For $\mathcal{W} \subset \mathbb{Z} \times[0, \infty)$ define the space-time inhomogeneous $\mathcal{W}$ restricted contact process $\xi_{t}^{\mathcal{W}}$ as follows. First, set $\xi_{t}^{\mathcal{W}}(x)=0$ for all $(x, t) \notin \mathcal{W}$. Second, for $(x, t) \in \mathcal{W}$, replace (1) with

$$
\begin{equation*}
1 \rightarrow 0 \text { at rate } 1 \quad \text { and } \quad 0 \rightarrow 1 \text { at rate } \lambda \sum_{y:|y-x|=1} \xi(y) 1_{\mathcal{W}}(y, t), \tag{5}
\end{equation*}
$$

so that infection spreads only between sites in the wedge. We will give an explicit graphical construction of $\xi_{t}^{\mathcal{W}}$ in Sect. 2. Our notation is slightly different from the standard one for which the superscript designates the initial state. For space-time regions $\mathcal{W}$, the notation $\xi_{t}^{\mathcal{W}}$ indicates the contact process with infection restricted to $\mathcal{W}$, and we will always explicitly state our choice of initial state $\xi_{0}^{\mathcal{W}}$.

For $0<\alpha_{l}<\alpha_{r}<\infty$ and nonnegative integers $M \geq 0$ define the "wedges" $\mathcal{W}=$ $\mathcal{W}\left(\alpha_{l}, \alpha_{r}, M\right)$ by

$$
\begin{equation*}
\mathcal{W}=\left\{(x, t) \in \mathbb{Z} \times[0, \infty): \alpha_{l} t \leq x \leq M+\alpha_{r} t\right\} \tag{6}
\end{equation*}
$$

In view of (4), we will impose the conditions

$$
\begin{equation*}
\lambda>\lambda_{c} \quad \text { and } \quad 0<\alpha_{l}<\alpha_{r}<\alpha(\lambda) . \tag{7}
\end{equation*}
$$

Our first result is that survival in wedges is possible.

Theorem 1 Assume (7) holds, $\mathcal{W}=\mathcal{W}\left(\alpha_{l}, \alpha_{r}, M\right)$, and $\xi_{0}^{\mathcal{W}}=[0, M] \cap \mathbb{Z}$. Then

$$
\begin{equation*}
\lim _{M \rightarrow \infty} P\left(\xi_{t}^{\mathcal{W}} \neq \emptyset \text { for all } t \geq 0\right)=1 \tag{8}
\end{equation*}
$$

When $\xi_{t}^{\mathcal{W}}$ survives it looks like the unrestricted contact process in equilibrium. To state this more precisely, let

$$
\begin{equation*}
r_{t}^{\mathcal{W}}=\max \left\{x: \xi_{t}^{\mathcal{W}}(x)=1\right\} \quad \text { and } \quad l_{t}^{\mathcal{W}}=\min \left\{x: \xi_{t}^{\mathcal{W}}(x)=1\right\}, \tag{9}
\end{equation*}
$$

and let $\hat{\xi}_{t}$ denote the contact process started in its upper invariant measure $\nu$. (That is, $\hat{\xi}_{0}$ is random with law $v$, and given $\hat{\xi}_{0}, \hat{\xi}_{t}$ makes transitions according to (1).)

Theorem 2 Assume $M \geq 1$ and (7) holds. Let $\mathcal{W}=\mathcal{W}\left(\alpha_{l}, \alpha_{r}, M\right)$ and assume $\xi_{0}^{\mathcal{W}}=$ $[0, M] \cap \mathbb{Z}$. On the event $\left\{\xi_{t}^{\mathcal{W}} \neq \emptyset\right.$ for all $\left.t \geq 0\right\}$,

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{r_{t}^{\mathcal{W}}}{t}=\alpha_{r} \quad \text { and } \quad \lim _{t \rightarrow \infty} \frac{l_{t}^{\mathcal{W}}}{t}=\alpha_{l} \text { a.s. } \tag{10}
\end{equation*}
$$

Furthermore, $\xi_{t}^{\mathcal{W}}$ and $\hat{\xi}_{t}$ can be coupled so that on the event $\left\{\xi_{t}^{\mathcal{W}} \neq \emptyset\right.$ for all $\left.t \geq 0\right\}$,

$$
\begin{equation*}
\xi_{t}^{\mathcal{W}}(x)=\hat{\xi}_{t}(x) \text { for all } x \in\left[l_{t}^{\mathcal{W}}, r_{t}^{\mathcal{W}}\right] \quad \text { for all large } t \text { a.s. } \tag{11}
\end{equation*}
$$

Theorem 2 is analogous to results for the unrestricted contact process, see Theorem VI.2.2 in [7].

Remark 3 It is not difficult to extend the argument used in the proof of Theorem VI.3.33 in [7] to show that for $a<b,\left|\hat{\xi}_{t} \cap[a t, b t]\right| / t \rightarrow(b-a) \rho(\lambda)$ a.s. as $t \rightarrow \infty$, where $\rho(\lambda)=v(\xi$ : $\xi(0)=1)$. Therefore Theorem 2 implies that if $\alpha_{l}<a<b<\alpha_{r}$, then when $\xi_{t}^{\mathcal{W}}$ survives, $\left|\xi_{t}^{\mathcal{W}} \cap[a t, b t]\right| / t \rightarrow(b-a) \rho(\lambda)$ a.s.

Theorem 1 can be used to obtain information about the "grass-bushes-trees" model (GBT) of [4]. In this model sites are either empty (0), occupied by a bush (1) or occupied by a tree (2). Both 1's and 2's turn to 0's at rate one. The 2's give birth at rate $\lambda_{2}$ on top of 1's and 0's. The 1's give birth at rate $\lambda_{1}$ on top of 0 's only, and hence are at a disadvantage compared to 2 's. The state space for the process is $\{0,1,2\}^{\mathbb{Z}}$, and the nearest-neighbor version of the model makes transitions at $x$ in state $\zeta$

$$
0 \rightarrow\left\{\begin{array} { l l } 
{ 1 } & { \text { at rate } \lambda _ { 1 } n _ { 1 } ( x , \zeta ) }  \tag{12}\\
{ 2 } & { \text { at rate } \lambda _ { 2 } n _ { 2 } ( x , \zeta ) }
\end{array} \quad 1 \rightarrow \left\{\begin{array}{ll}
0 & \text { at rate } 1 \\
2 & \text { at rate } \lambda_{2} n_{2}(x, \zeta)
\end{array} \quad 2 \rightarrow 0 \text { at rate } 1\right.\right.
$$

A natural question to ask is whether or not coexistence of 1 's and 2 's is possible. It was shown in [4] that coexistence is possible for a non-nearest neighbor version of the model and appropriate $\lambda_{i}$, where coexistence meant that $\zeta_{t}$ had a stationary distribution $\mu$ such that

$$
\begin{equation*}
\mu\left(\left\{\zeta:\|\zeta\|_{i}=\infty \text { for } i=1,2\right\}\right)=1 \tag{13}
\end{equation*}
$$

It was also shown in [4] that there is no stationary distribution satisfying (13) in the nearestneighbor case for any choice of the $\lambda_{i}$. Moreover, if there are infinitely many 2 's initially then for each site there is a last time at which a 1 can be present. Nevertheless, it is a consequence of Theorem 1 and the construction used in its proof that a form of weak coexistence is possible, even starting from a single 1 and infinitely many 2 's.

Corollary 4 Let $\zeta_{t}$ be the GBT process with initial state $\zeta_{0}$, where $\zeta_{0}(x)=2$ for $x<0$, $\zeta_{0}(0)=1$ and $\zeta_{0}(x)=0$ for $x>0$. For all $\lambda_{c}<\lambda_{2}<\lambda_{1}$,

$$
\begin{equation*}
P\left(\lim _{t \rightarrow \infty}\left\|\zeta_{t}\right\|_{1}=\infty\right)>0 \tag{14}
\end{equation*}
$$

The 2 's spread to the right at rate $\alpha\left(\lambda_{2}\right)$, ignoring the 1 's, while the 1 's try to spread to the right at the faster rate $\alpha\left(\lambda_{1}\right)$. The 1's will be killed by 2 's invading from the left, but Theorem 1 shows that they can survive with positive probability by moving off to the right in the space-time region free of 2's.

Remark 5 (1) Corollary 4 is proved by showing that the set of 1 's in $\zeta_{t}$ dominates an appropriate wedge-restricted contact process with positive probability. By working harder one can use this idea and Theorem 2 to obtain more information about the set of 1's in $\zeta_{t}$, but we will not pursue this here. (2) Our model is a stochastic process in an inhomogeneous environment. There are numerous papers in the physics literature regarding such models, see for instance [2,10] and [9] and more recently in the mathematical biology literature, see [1]. Closer to this paper is the work on non-oriented percolation in various subsets of $\mathbb{Z}^{d}$ that has been studied in [5] and in [3], but as far as we are aware our results on oriented percolation are new.

In Sect. 2 we give the standard graphical construction due to Harris, then prove Theorem 1 in Sect. 3, Theorem 2 in Sect. 4, and Corollary 4 in Sect. 5.

## 2 The Graphical Representation

For $x \in \mathbb{Z}$ let $\left\{T_{n}^{x}: n \geq 1\right\}$ be the arrival times of a Poisson process with rate 1 , and for all pairs of nearest-neighbor sites $x, y$ let $\left\{B_{n}^{x, y}: n \geq 1\right\}$ be the arrival times of a Poisson process with rate $\lambda$. The Poisson processes $T^{x}, B^{x, y}, x, y \in \mathbb{Z}$, are all independent. At the times $T_{n}^{x}$ we put a $\delta$ at site $x$ to indicate a death at $x$, and at the times $B_{n}^{x, y}$ we draw an arrow from $x$ to $y$, indicating that a 1 at $x$ will give birth to a 1 at $y$. For $0 \leq s<t$ and sites $x, y$ we say that there is an active path up from $(x, s)$ to $(y, t)$ if there is a sequence of times $t_{0}=s \leq t_{1}<t_{2}<\cdots<t_{n} \leq t_{n+1}=t$ and a sequence of sites $x_{0}=x, x_{1}, \ldots, x_{n}=y$ such that

1. if $n \geq 1$, then for $i=1,2 \ldots, n,\left|x_{i}-x_{i-1}\right|=1$ and there is an arrow from $x_{i-1}$ to $x_{i}$ at time $t_{i}$
2. for $i=0 \ldots, n$, the time segments $\left\{x_{i}\right\} \times\left[t_{i}, t_{i+1}\right]$ do not contain any $\delta$ 's

By default there is always an active path up from $(y, t)$ to $(y, t)$. For a space-time region $\mathcal{W} \subset \mathbb{Z} \times[0, \infty)$ we define $\xi_{t}^{\mathcal{W}}$, the contact process restricted to $\mathcal{W}$, as follows. Given an initial state $\xi_{0} \subset\{x:(x, 0) \subset \mathcal{W}\}$, set $\xi_{t}(y)=0$ for all $(y, t) \notin \mathcal{W}$. If there is a site $x$ with $\xi_{0}(x)=1$ and an active path up from $(x, 0)$ to $(y, t)$ lying entirely in $\mathcal{W}$ set $\xi_{t}^{\mathcal{W}}(y)=$ 1 , otherwise set $\xi_{t}^{\mathcal{W}}(y)=0$. For $\mathcal{W}=\mathbb{Z} \times[0, \infty)$ we will write $\xi_{t}$ and refer to it as the unrestricted process.

We may also construct the GBT process $\zeta_{t}$ with the above Poisson processes and the help of some additional independent coin flips. Fix $\lambda_{c}<\lambda_{2}<\lambda_{1}$, and suppose $\lambda=\lambda_{1}$ in the construction just given. Independently of everything else, label the arrows determined by the $B_{n}^{x y}$ with a " 1 -only" sign with probability $\left(\lambda_{1}-\lambda_{2}\right) / \lambda_{1}$. Call an active path up from $(x, s)$ to ( $y, t$ ) a 2-path if none of its arrows are 1 -only arrows. Given $\zeta_{0}$, we may now construct
$\zeta_{t}$ as follows. (i) For all $t>0$ and $x \in \mathbb{Z}$, put $\zeta_{t}(x)=2$ if for some site $y$ with $\zeta_{0}(y)=2$ there is an active 2-path up from $(y, 0)$ to $(x, t)$. (ii) If we have not already set $\xi_{t}(x)=2$, put $\zeta_{t}(x)=1$ if for some site $y$ with $\zeta_{0}(y)=1$ there is an active path up from $(y, 0)$ to ( $x, t$ ) with the property that no vertical segments in the path contain a point $(z, u)$ such that $\zeta_{u}(z)=2$. (iii) For all other $(x, t)$, put $\zeta_{t}(x)=0$. A little thought shows that $\zeta_{t}$ is the GBT process with the rates given in (12). The process of 2's is a contact process with infection parameter $\lambda_{2}$, and in the absence of 2 's, the process of 1 's is a contact process with infection parameter $\lambda_{1}$.

## 3 Proof of Theorem 1

The Space-Time Regions $\mathcal{Y}_{j k}$ We will modify somewhat the standard approach of constructing a mapping from appropriate space-time regions of the construction just given to an oriented-percolation model with the property that survival of the percolation process implies survival of the contact process. We will call the regions $\mathcal{Y}_{j k}$, they will be defined using the parallelograms of Sect. VI. 3 of [7]. We will make use of the following notation: for $x \mathbb{R}^{2}$ and $A \subset \mathbb{R}^{2}, x+A=\{x+a: a \in A\}$, the translate of $A$ by $x$.

Let $\mathcal{L}$ be the lattice $\mathcal{L}=\left\{(j, k) \in \mathbb{Z}^{2}: k \geq 0\right.$ and $j+k$ is even $\}$ with norm $\|(j, k)\|=$ $1 / 2(|j|+|k|)$. Fix $0<\beta<\alpha / 3$ and $M>0$ so that $M \beta / 2$ and $M \alpha$ are integers. Later we will set $\alpha=\alpha(\lambda)$ and take $\beta$ small. For $(j, k) \in \mathcal{L}, L_{j k}$ and $R_{j k}$ are the "large" space-time parallelograms in $\mathbb{Z} \times[0, \infty)$ given by:

$$
L_{j k}=(M j(\alpha-\beta), M k)+L_{00}, \quad R_{j k}=(M j(\alpha-\beta), M k)+R_{00}
$$

where

$$
\begin{aligned}
L_{00} & =\{(x, t) \in \mathbb{Z} \times[0, M(1+\beta / \alpha)]: M \beta / 2 \leq x+\alpha t \leq 3 M \beta / 2\} \\
R_{00} & =\{(x, t) \in \mathbb{Z} \times[0, M(1+\beta / \alpha)]:-3 M \beta / 2 \leq x-\alpha t \leq-M \beta / 2\} .
\end{aligned}
$$

Observe that $L_{j k}\left(R_{j k}\right)$ is simply a translation of $L_{00}\left(R_{00}\right)$ by the vector $(M j(\alpha-\beta), M k)$. We will also need the "small" parallelograms

$$
L_{j k}^{\text {small }}=(M j(\alpha-\beta), M k)+L_{00}^{\text {small }}, \quad R_{j k}^{\text {small }}=(M j(\alpha-\beta), M k)+R_{00}^{\text {small }}
$$

where

$$
\begin{aligned}
& L_{00}^{\text {small }}=\left\{(x, t) \in \mathbb{Z} \times\left[0, M \frac{3 \beta}{2 \alpha}\right]: M \beta / 2 \leq x+\alpha t \leq 3 M \beta / 2\right\} \\
& R_{00}^{\text {small }}=\left\{(x, t) \in \mathbb{Z} \times\left[0, M \frac{3 \beta}{2 \alpha}\right]:-3 M \beta / 2 \leq x-\alpha t \leq-M \beta / 2\right\} .
\end{aligned}
$$

It is important to note that $L_{00}^{\text {small }} \subset L_{00}, R_{00}^{\text {small }} \subset R_{00}$, and

$$
R_{j k} \cap L_{j k}=R_{j k} \cap L_{j k}^{\text {small }}=R_{j k}^{s m a l l} \cap L_{j k}
$$

as shown in Fig. 1.
We can now define the new objects $\mathcal{Y}_{j k}$ which will be used to construct our oriented percolation process. As is the case with the parallelograms, the $\mathcal{Y}_{j k}$ will be certain translates


Fig. 1 (Color online) Large parallelograms $L_{00}$ and $R_{00}$. The shaded region is $L_{00}^{\text {small }}$


Fig. $2 \mathcal{Y}_{00}$ with $\ell=5, d=0,1,2$
of $\mathcal{Y}_{00}$, and depend on two fixed integers $\ell, d$ which satisfy $\ell \geq 2$ and $d \geq 0$ with $\ell>d$ (the dependence on $\ell, d$ will be surpressed from the notation). We will form $\mathcal{Y}_{00}$ by sticking together $\ell$ big right parallelograms, connected with appropriate small left parallelograms, and then two branches of $d$ and $d+1$ big left parallelograms connected by small right parallelograms. Figure 2 shows examples of $\mathcal{Y}_{00}$ with parameters $\ell=5$ and $d=0,1,2$. It seems simplest to define $\mathcal{Y}_{00}$ in stages, beginning with $\mathcal{Y}_{00}^{0}=R_{00}$.

1. Attach $\ell$ big right parallelograms with $\ell$ small parallelograms to connect them:

$$
\mathcal{Y}_{00}^{1}=\mathcal{Y}_{00}^{0} \cup\left(\bigcup_{i=1}^{\ell}\left(R_{i i} \cup L_{i i}^{s m a l l}\right)\right) .
$$

2. Attach one big left parallelogram: $\mathcal{Y}_{00}^{2}=\mathcal{Y}_{00}^{1} \cup L_{\ell, \ell}$.
3. If $d=0$ set $\mathcal{Y}_{00}=\mathcal{Y}_{00}^{2}$. If $d \geq 1$, attach another big left parallelogram:

$$
\mathcal{Y}_{00}^{3}=\mathcal{Y}_{00}^{2} \cup L_{\ell+1, \ell+1} .
$$

4. If $d=1$, attach another big left and small right parallelogram:

$$
\mathcal{Y}_{00}^{4}=\mathcal{Y}_{00}^{3} \cup\left(L_{\ell-1, \ell+1} \cup R_{\ell-1, \ell+1}^{s m a l l}\right)
$$

and set $\mathcal{Y}_{00}=\mathcal{Y}_{00}^{4}$. If $d \geq 2$, attach two branches, to reach "height" $\ell+d+1$, of big left parallelograms with small right parallelograms as connectors:

$$
\mathcal{Y}_{00}^{4}=\mathcal{Y}_{00}^{3} \cup\left(\bigcup_{i=0}^{d-1}\left(L_{\ell-i, \ell+i} \cup R_{\ell-i, \ell+i}^{\text {small }}\right) \cup\left(L_{\ell+1-i, \ell+1+i} \cup R_{\ell+1-i, \ell+1+i}^{\text {small }}\right)\right) .
$$

5. If $d \geq 2$, attach a final big left parallelogram and small right parallelogram:

$$
\mathcal{Y}_{00}^{5}=\mathcal{Y}_{00}^{4} \cup L_{\ell-d, \ell+d} \cup R_{\ell-d, \ell+d}^{\text {small }}
$$

and put $\mathcal{Y}_{00}=\mathcal{Y}_{00}^{5}$.
Having defined $\mathcal{Y}_{00}$ we set

$$
\mathcal{Y}_{j k}=(M[k(\ell-d)+j](\alpha-\beta), M k(\ell+d+1))+\mathcal{Y}_{00}, \quad(j, k) \in \mathcal{L} .
$$

The Percolation Variables $U_{j k}$ Given $\ell, d$ and the objects $\mathcal{Y}_{j k}$, let $\mathcal{O}_{j k}$ be the event that for every parallelogram $\mathcal{P}$ in $\mathcal{Y}_{j k}$ there is an active path in the graphical representation of the contact process which stays entirely in $\mathcal{P}$ and connects some point in the bottom edge of $\mathcal{P}$ to some point in the top edge of $\mathcal{P}$. Thus on $\mathcal{O}_{j k}$ there is some point in the bottom edge of $\mathcal{Y}_{j k}$ with the property that there are active paths in $\mathcal{Y}_{j k}$ connecting this point to the top edge of every parallelogram in $\mathcal{Y}_{j k}$, and in particular to the top edges of the two top parallelograms $\mathcal{Y}_{j k}$. This means that on $\mathcal{O}_{j k}$ there is a point in the bottom edge of $\mathcal{Y}_{j k}$ and active paths in $\mathcal{Y}_{j k}$ connecting this point to the bottom edges of both $\mathcal{Y}_{j-1, k+1}$ and $\mathcal{Y}_{j+1, k+1}$.

It is a consequence of Lemma VI.3.17 in [7] that $P\left(\mathcal{O}_{00}\right)$ is close to 1 for large $M$.
Lemma 6 For $0<\beta<\alpha / 3$ and fixed $\ell, d, \lim _{M \rightarrow \infty} P\left(\mathcal{O}_{00}\right)=1$.
Proof As in [7] let $\mathcal{E}_{j k}$ be the event that there is an active path in the graphical representation of the contact process which goes from the bottom edge of $R_{j k}$ to the top edge, always staying entirely within $R_{j k}$, and also that there is an active path from the bottom edge of $L_{j k}$ to the top edge, always staying entirely within $L_{j k}$. It is clear that the probability of connecting the bottom edge of a small parallelogram to its top edge by an active path staying in the parallelogram is bounded below by $P\left(\mathcal{E}_{00}\right)$. By Lemma 3.17 in [7], for $0<\beta<$ $\alpha / 3, \lim _{M \rightarrow \infty} P\left(\mathcal{E}_{00}\right)=1$. In the construction of $\mathcal{Y}_{00}$ there are most $h=2 \ell+4 d$ (if $d \geq 1$ ) or $h=2 \ell+1$ (if $d=0$ ) parallelograms used. It follows from positive correlations that $P\left(\mathcal{O}_{00}\right) \geq P\left(\mathcal{E}_{j k}\right)^{h}$, and thus $\lim _{M \rightarrow \infty} P\left(\mathcal{O}_{00}\right)=1$

For $(j, k) \in \mathcal{L}$ let $U_{j k}=1_{\mathcal{O}_{j k}}$. Then $P\left(U_{j k}=1\right)=P\left(\mathcal{O}_{00}\right)$ does not depend on $(j, k)$. Furthermore, the $U_{j k}$ are 1-dependent, meaning that if $I \subset \mathcal{L}$ is such that $\left\|(j, k)-\left(j^{\prime}, k^{\prime}\right)\right\|>$ 1 for all $(j, k) \neq\left(j^{\prime}, k^{\prime}\right) \in I$, then the $U_{j k},(j, k) \in I$ are independent. This is because the corresponding space-time regions $\mathcal{Y}_{j k}, \mathcal{Y}_{j^{\prime} k^{\prime}}$ are disjoint. Using the $U_{j k}$ we may construct a 1 -dependent oriented percolation process in the usual way. A path in $\mathcal{L}$ is a sequence $\left(j_{1}, k_{1}\right), \ldots,\left(j_{n}, k_{n}\right)$ of points of $\mathcal{L}$ which satisfies $k_{i+1}=k_{i}+1$ and $j_{i+1}=j_{i} \pm 1$ for all $1 \leq i \leq n-1$. The path is said to be open if $U_{j_{i}, k_{i}}=1$ for each $1 \leq i \leq n-1$. It is clear from the properties of the $\mathcal{O}_{j k}$ that if $\left(j_{1}, k_{1}\right), \ldots,\left(j_{n}, k_{n}\right)$ is an open path in $\mathcal{L}$ then there must be


Fig. 3 (Color online) $\mathcal{Y}_{00}, \mathcal{Y}_{1,1}, \mathcal{Y}_{-1,1}$
an active path in the graphical representation from the bottom edge of $\mathcal{Y}_{j_{1}, k_{1}}$ to the bottom edge of $\mathcal{Y}_{j_{n}, k_{n}}$.

If we let $\Omega_{\infty}$ be the event that there is an infinite open path in $\mathcal{L}$ starting at $(0,0)$, then by Lemma 6 above and Theorem VI.3.19 of [7],

$$
\begin{equation*}
\lim _{M \rightarrow \infty} P\left(\Omega_{\infty}\right)=1 . \tag{15}
\end{equation*}
$$

Survival of $\xi_{t}^{\mathcal{W}} \quad$ Let $\mathcal{Y}=\mathcal{Y}(\ell, d, M)=\bigcup_{k=0}^{\infty} \bigcup_{j=-k}^{k} \mathcal{Y}_{j k}$. On $\Omega_{\infty}$ there must be an infinite active path in the graphical representation starting at some $(x, 0), x \in[-3 M \beta / 2,-M \beta / 2]$, which lies entirely in $\mathcal{Y}$. Thus if $\mathcal{W}$ is any space-time region such that $\mathcal{Y} \subset \mathcal{W}$, and $\xi_{t}^{\mathcal{W}}$ is the $\mathcal{W}$-restricted contact process starting from $\{x:(x, 0) \subset \mathcal{W}\}$, then $\xi_{t}^{\mathcal{W}} \neq \emptyset \forall t \geq 0$ on $\Omega_{\infty}$. We will prove the following.

Claim Assume (7) holds and $\alpha=\alpha(\lambda)$. Then there exists $0<\beta<\alpha / 3$ and integers $\ell^{\prime}, d^{\prime}$ such that for all $M>0$,

$$
\begin{equation*}
\mathcal{Y}\left(\ell^{\prime}, d^{\prime}, M / \alpha\left(\ell^{\prime}+3\right)\right) \subset \mathcal{W}\left(\alpha_{l}, \alpha_{r}, M\right)-\left(M /\left(\ell^{\prime}+3\right), 0\right) . \tag{16}
\end{equation*}
$$

Given (16), it follows from translation invariance and (15) that

$$
P\left(\xi_{t}^{\mathcal{W}\left(\alpha_{l}, \alpha_{r}, M\right)} \neq \emptyset \forall t \geq 0\right) \geq P\left(\Omega_{\infty}\right) \rightarrow 1 \quad \text { as } M \rightarrow \infty,
$$

proving (8).

To prove (16) we first suppose that $\ell, d$, are positive integers with $d<\ell$ and $M>0$. For $(j, k) \in \mathcal{L}$, the left upper corner of $L_{j k}$ is $(M(j(\alpha-\beta)-\alpha-\beta / 2), M(k+1+\beta / \alpha)$ ), and the right bottom corner of $L_{j k}$ is $(M(j(\alpha-\beta)+3 \beta / 2), M k)$. A little thought shows that $\mathcal{Y}$ must be contained in the space-time region bounded by the following two lines and the $x$-axis. The first line connects the leftmost point of the top edge of $\mathcal{Y}_{00}$ with the leftmost point of the top edge of $\mathcal{Y}_{-1,1}$, which are the left upper corner of $L_{\ell-d, \ell+d}$ and the left upper corner of $L_{2(\ell+d)-1,2(\ell+d)+1}$, namely, the points

$$
(M((\ell-d)(\alpha-\beta)-\alpha-\beta / 2), M(\ell+d+1+\beta / \alpha))
$$

and

$$
(M(2(\ell-d)(\alpha-\beta)-2 \alpha+\beta / 2), M(2(\ell+d+1)+\beta / \alpha)) .
$$

The slope of this line is

$$
\begin{equation*}
s_{l}=\frac{\ell+d+1}{\ell-d-1} \frac{1}{\alpha-\beta} \tag{17}
\end{equation*}
$$

and it contains the point $\left(x_{l}, 0\right)$ where $x_{l}=-M\left(3 \beta / 2+\beta / \alpha s_{l}\right)$. The second line connects the rightmost point of $\mathcal{Y}_{00}$ with the rightmost point of $\mathcal{Y}_{1,1}$, the bottom right corner of $L_{\ell+1, \ell+1}$ and the bottom right $L_{2(\ell+1)-d, 2(\ell+1)+d}$, namely, the points

$$
(M((\ell+1)(\alpha-\beta)+3 \beta / 2), M(\ell+1))
$$

and

$$
(M((2(\ell+1)-d)(\alpha-\beta)+3 \beta / 2), M(2(\ell+1)+d)) .
$$

The slope of this line is

$$
\begin{equation*}
s_{r}=\frac{\ell+d+1}{\ell-d+1} \frac{1}{\alpha-\beta} \tag{18}
\end{equation*}
$$

and it contains the point $\left(x_{r}, 0\right)$ where $x_{r}=M\left((\ell+1)\left(\alpha-\beta-1 / s_{r}\right)+3 \beta / 2\right)$.
This analysis shows that $\mathcal{Y}(\ell, d, M)$ is contained in the wedge $\mathcal{W}\left(1 / s_{l}, 1 / s_{r}, M^{\prime}\right)+$ $\left(x_{l}, 0\right)$, where $M^{\prime}=x_{r}-x_{l}$. A little algebra shows that $-M \alpha<x_{l}<x_{r}<M \alpha(\ell+2)$, and thus

$$
\begin{equation*}
\mathcal{Y}(\ell, d, M) \subset \mathcal{W}\left(1 / s_{l}, 1 / s_{r}, M \alpha(\ell+3)\right)-(M \alpha, 0) . \tag{19}
\end{equation*}
$$

We now set $s_{\ell}=1 / \alpha_{\ell}, s_{r}=1 / \alpha_{r}$ and solve (17) and (18) for $d$ and $\ell$, obtaining

$$
\begin{equation*}
\ell=\frac{s_{r}\left(s_{l}(\alpha-\beta)+1\right)}{s_{l}-s_{r}}, \quad d=\frac{s_{l}\left(s_{r}(\alpha-\beta)-1\right)}{s_{l}-s_{r}} . \tag{20}
\end{equation*}
$$

Unfortunately, $\ell, d$ need not be integers. To deal with this problem we first note that if $s_{l} \geq s_{l}^{\prime}>s_{r}$ then for any $M$, the wedge $\mathcal{W}\left(\alpha_{l}, \alpha_{r}, M\right)$ contains the narrower wedge $\mathcal{W}\left(1 / s_{\ell}^{\prime}, 1 / s_{r}, M\right)$. If we can find $s_{\ell}^{\prime}$ and $0<\beta<\alpha / 3$ such that

$$
\begin{equation*}
\ell^{\prime}=\frac{s_{r}\left(s_{l}^{\prime}(\alpha-\beta)+1\right)}{s_{l}^{\prime}-s_{r}} \quad \text { and } \quad d^{\prime}=\frac{s_{l}^{\prime}\left(s_{r}(\alpha-\beta)-1\right)}{s_{l}^{\prime}-s_{r}} \tag{21}
\end{equation*}
$$

are both integers, then (16) follows from (19).
We can find $s_{\ell}^{\prime}, \beta$ as follows. Let $m_{0}=3 / \alpha s_{r}$ and take any integer $m>m_{0}$ such that $s_{r} \frac{m}{m-1}<s_{l}$. Put $s_{l}^{\prime}=s_{r} \frac{m}{m-1}$, so that $s_{l}>s_{l}^{\prime}>s_{r}$. Since $m>3 / \alpha s_{r}, 1 / 3 \alpha m s_{r}>1$ and the


Fig. 4 (Color online) Wedge containing $\mathcal{Y}$
interval $\left(\frac{2}{3} \alpha m s_{r}, \alpha m s_{r}\right)$ must contain at least one integer. Since $\alpha s_{r}>1$, the right endpoint of this interval is greater than $m$. Choose any integer $c \geq m$ from the interval and put $\beta=$ $\alpha-\frac{c}{m s_{r}}$. Then $0<\beta<\alpha / 3$ and $s_{r}(\alpha-\beta)=c / m$. A little algebra shows that $\ell^{\prime}, d^{\prime}$ given in (21) are the integers $\ell^{\prime}=c+m-1, d^{\prime}=c-m$, and we are done.

## 4 Proof of Theorem 2

We begin by analyzing the rightmost particle. Let $\mathcal{W}\left(\alpha_{r}, M\right)=\{(x, t): t \geq 0, x \in$ $\left.\left(-\infty, M+\alpha_{r} t\right] \cap \mathbb{Z}\right\}$ and consider the restricted contact process $\xi_{t}^{\mathcal{W}\left(\alpha_{r}, M\right)}$ with initial state $\xi_{0}^{\mathcal{W}\left(\alpha_{r}, M\right)}=(-\infty, M] \cap \mathbb{Z}$. Let $\bar{r}_{t}^{M}$ be the corresponding right-edge process, $\bar{r}_{t}^{M}=\max \{x$ : $\left.\xi_{t}^{\mathcal{N}\left(\alpha_{r}, M\right)}(x)=1\right\}$. We claim that for every $M$,

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{\bar{r}_{t}^{M}}{t}=\alpha_{r} \quad \text { a.s. } \tag{22}
\end{equation*}
$$

By stationarity of the basic Poisson processes, the law of $\bar{r}^{M+1}$ is the same as the law of $\bar{r}^{M}+1$, so it suffices to prove (22) for $M=0$. By construction, $\limsup _{t \rightarrow \infty} \bar{r}_{t}^{0} / t \leq \alpha_{r}$ a.s.

For the lower bound, fix $0<\varepsilon<\alpha_{r}$ and consider the region $\mathcal{W}\left(\alpha_{r}-\varepsilon, \alpha_{r}, M\right)$ and the restricted contact process $\xi_{t}^{\mathcal{W}\left(\alpha_{r}-\varepsilon, \alpha_{r}, M\right)}$ with initial state $[0, M] \cap \mathbb{Z}$. For fixed $\delta>0$, Theorem 1 implies there exists $M_{0}$ such that the event $\left\{\xi_{t}^{\mathcal{W}\left(\alpha_{r}-\varepsilon, \alpha_{r}, M_{0}\right)} \neq \emptyset \forall t \geq 0\right\}$ has probability at least $1-\delta$. On this event, since $\xi_{t}^{\mathcal{\mathcal { W } ( \alpha _ { r } - \varepsilon , \alpha _ { r } , M _ { 0 } )}} \subset \xi_{t}^{\mathcal{W}\left(\alpha_{r}, M_{0}\right)}, \liminf _{t \rightarrow \infty} \bar{r}_{t}^{M_{0}} / t \geq \alpha_{r}-\varepsilon$. Consequently,

$$
P\left(\liminf _{t \rightarrow \infty} \bar{r}_{t}^{0} / t \geq \alpha_{r}-\varepsilon\right)=P\left(\liminf _{t \rightarrow \infty} \bar{r}_{t}^{M_{0}} / t \geq \alpha_{r}-\varepsilon\right) \geq 1-\delta
$$

This shows $P\left(\liminf _{t \rightarrow \infty} \bar{r}_{t}^{0} / t \geq \alpha_{r}-\varepsilon\right)=1$ for every $\varepsilon>0$, and together with the previous limsup bound shows $\vec{r}_{t}^{0} / t \rightarrow \alpha_{r}$ a.s., establishing (22).

It is a consequence of the nearest-neighbor interaction mechanism that for any $\alpha_{l}<\alpha_{r}$ and $M$, with $\mathcal{W}=\mathcal{W}\left(\alpha_{l}, \alpha_{r}, M\right)$,

$$
\xi_{t}^{\mathcal{W}}(x)=\xi_{t}^{\mathcal{W}\left(\alpha_{r}, M\right)}(x) \quad \forall x \in\left[l_{t}^{\mathcal{W}}, r_{t}^{\mathcal{W}}\right] \quad \text { on } \quad\left\{\xi_{t}^{\mathcal{W}} \neq \emptyset\right\}
$$

This implies $r_{t}^{\mathcal{W}}=\bar{r}_{t}^{M}$ on $\left\{\xi_{t}^{\mathcal{W}} \neq \emptyset\right\}$, and so by (22), $\lim _{t \rightarrow \infty} r_{t}^{\mathcal{W}} / t=\alpha_{r}$ on the event $\left\{\xi_{t}^{\mathcal{W}} \neq\right.$ $\emptyset \forall t \geq 0\}$. We omit the similar argument for $\lim _{t \rightarrow \infty} l_{t}^{\mathcal{W}} / t=\alpha_{l}$.

For (11), let $\xi_{t}^{\mathbb{Z}}$ denote the unrestricted process with initial state $\xi_{0}^{\mathbb{Z}}=\mathbb{Z}$, and let $\hat{\xi}_{t}$ be the unrestricted process constructed in Sect. 2 started in the invariant measure $\nu$. (That is, $\hat{\xi}_{0}$ is random with law $v$, independent of the Poisson processes, and given $\hat{\xi}_{0}$ the construction of Sect. 2 is used.) We observe again that the nearest-neighbor interaction implies

$$
\xi_{t}^{\mathbb{Z}}(x)=\xi_{t}^{\mathcal{W}}(x) \quad \forall x \in\left[l_{t}^{\mathcal{W}}, r_{t}^{\mathcal{W}}\right] \quad \text { on } \quad\left\{\xi_{t}^{\mathcal{W}} \neq \emptyset \forall t \geq 0\right\}
$$

Standard exponential estimates for $P\left(\xi_{t}^{\mathbb{Z}}(x) \neq \hat{\xi}_{t}(x)\right)=P\left(\xi_{t}^{\mathbb{Z}}(x)=1\right)-P\left(\hat{\xi}_{t}(x)=1\right)$, a "filling in" argument and Borel-Cantelli (see Theorem I.2.30 of [8]) imply that for any $A>0$,

$$
P\left(\xi_{t}^{\mathbb{Z}}=\hat{\xi}_{t} \text { on }[-A t, A t] \text { for all large } t\right)=1
$$

Combining the above with (10) gives (11).

## 5 Proof of Corollary 4

We will make use of the graphical construction in Sect. 2 and define independent events $\Omega_{1}, \Omega_{2}, \Omega_{3}$, each with positive probability, and such that $\left\|\zeta_{t}\right\|_{1} \rightarrow \infty$ as $t \rightarrow \infty$ on their intersection.

First, since $\alpha(\lambda)$ is strictly increasing we may choose $\alpha\left(\lambda_{2}\right)<\alpha_{l}<\alpha_{r}<\alpha\left(\lambda_{1}\right)$. Fix $M>2$ and write $\mathcal{W}$ for $\mathcal{W}\left(\alpha_{l}, \alpha_{r}, M\right)$. The first event is
$\Omega_{1}=\left\{\right.$ there is no active 2-path from any $(x, 0), x<0$, to any point of $\left.\mathcal{W}\left(\alpha_{l}, \alpha_{r}, M\right)\right\}$.
Since the process of 2 's is a contact process with parameter $\lambda_{2}$, and $\alpha\left(\lambda_{2}\right)<\alpha_{l}$, it follows from (4) that $\Omega_{1}$ has positive probability.

For the second event, choose $x_{0} \in \mathbb{Z}$ and $t_{0}>0$ such that $x_{0}=\alpha_{l} t_{0}$ and $\left(x, t_{0}\right) \subset \mathcal{W}$ for all $x \in\left[x_{0}, x_{0}+M\right] \cap \mathbb{Z}$. Since $M>2$ the event,
$\Omega_{2}=\left\{\right.$ there is an active path in $\mathcal{W}$ from $(0,0)$ to each of $\left.\left(x, t_{0}\right), x \in\left[x_{0}, x_{0}+M\right] \cap \mathbb{Z}\right\}$
has positive probability.
For the third event, define, for $t \geq t_{0}$,

$$
\begin{aligned}
& A_{t}=\left\{y: \text { there is an infinite active path in } \mathcal{W} \text { from }\left(x, t_{0}\right) \text { to }(y, t)\right. \\
& \\
& \left.\quad \text { for some } x \in\left[x_{0}, x_{0}+M\right] \cap \mathbb{Z}\right\}
\end{aligned}
$$

and put $\Omega_{3}=\left\{\left|A_{t}\right| \rightarrow \infty\right.$ as $\left.t \rightarrow \infty\right\}$. It follows from Theorems 1 and 2 that $\Omega_{3}$ has positive probability.

The events $\Omega_{i}$ are independent since they are defined in terms of our Poisson processes over disjoint space-time regions. Furthermore, it is easy to see from Remark 3 that $\left\|\zeta_{t}\right\|_{1} \rightarrow$ $\infty$ on their intersection, so we are done.

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